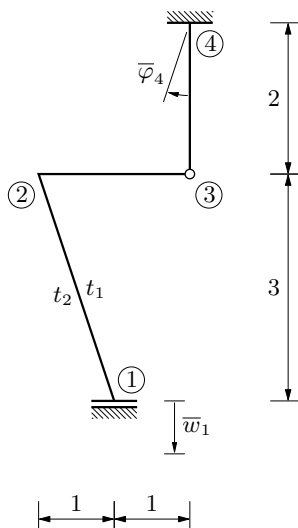


Inženjerska metoda pomakā

Primjer

Nacrtajte dijagram momenata savijanja!



$$\bar{w}_1 = 3 \text{ mm}$$

$$\bar{\varphi}_4 = 0,0006$$

$$t_1 = 0^\circ \text{ C}$$

$$t_2 = 42^\circ \text{ C}$$

$$\alpha_t = 10^{-5} \text{ K}^{-1}$$

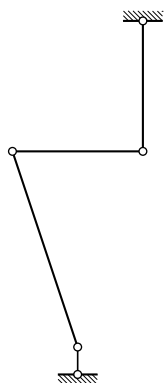
$$EI = 162\,000 \text{ kNm}^2$$

$$(EI)_{\{2,3\}} = (EI)_{\{3,4\}} = EI$$

$$(EI)_{\{1,2\}} = 2EI$$

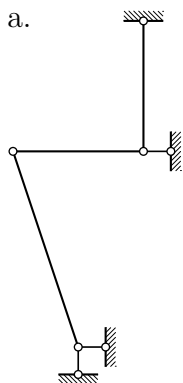
$$h_{\{1,2\}} = 60 \text{ cm}$$

nepoznanice:



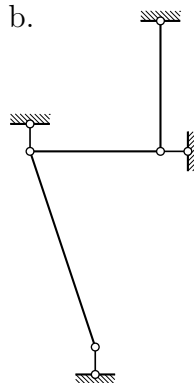
$$S_{\min} = 3 \cdot 2 - 4$$

$$= 2$$



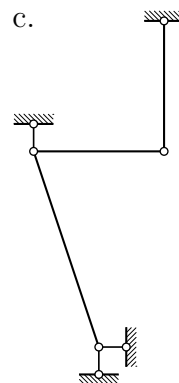
$$\varphi_2$$

$$u_1, u_{\{2,3\}}$$



$$\varphi_2$$

$$w_2, u_{\{2,3\}}$$



$$\varphi_2$$

$$u_1, w_2$$

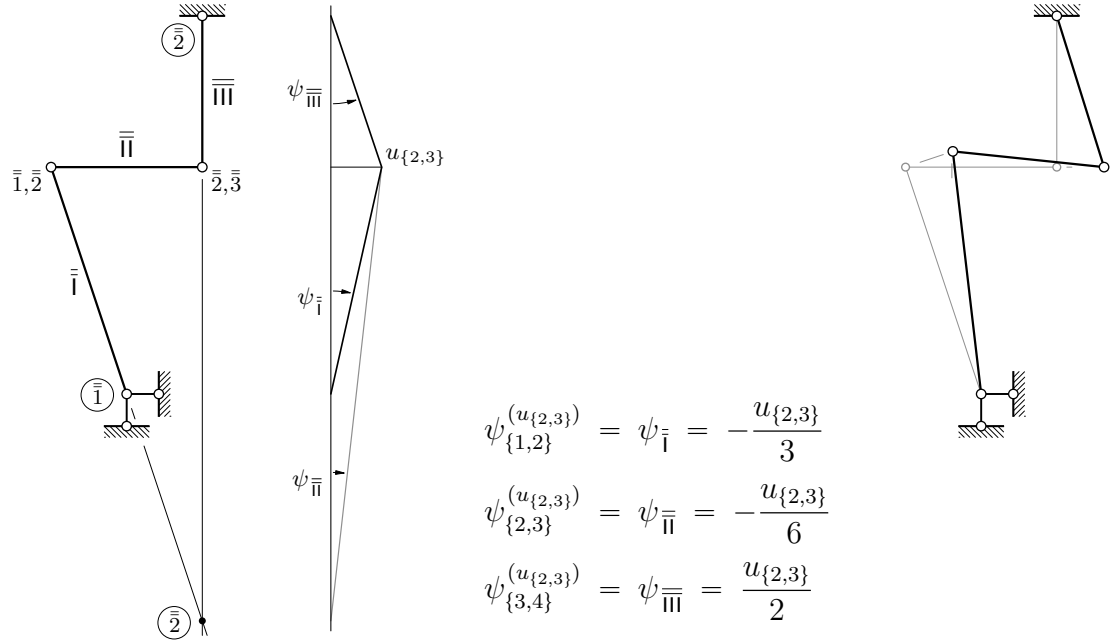
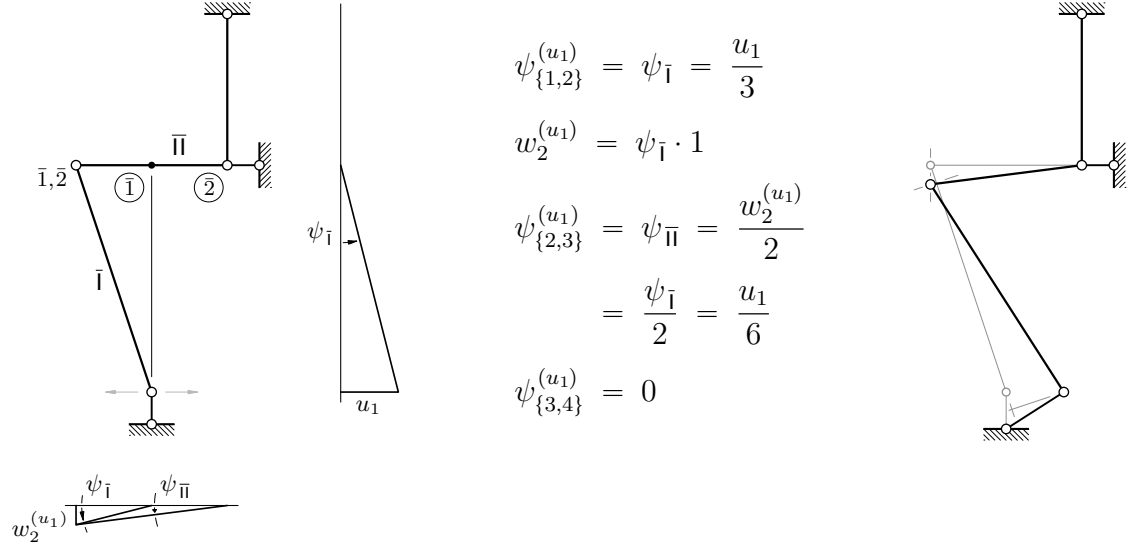
a.

$$M_{1,2} = 2k_{\{1,2\}}\varphi_2 - 6k_{\{1,2\}}\psi_{\{1,2\}}^{(u_1)} - 6k_{\{1,2\}}\psi_{\{1,2\}}^{(u_{\{2,3\}})} + \bar{M}_{1,2}$$

$$M_{2,1} = 4k_{\{1,2\}}\varphi_2 - 6k_{\{1,2\}}\psi_{\{1,2\}}^{(u_1)} - 6k_{\{1,2\}}\psi_{\{1,2\}}^{(u_{\{2,3\}})} + \bar{M}_{2,1}$$

$$M_{2,3} = M_{2,3}^c = 3k_{\{2,3\}}\varphi_2 - 3k_{\{2,3\}}\psi_{\{2,3\}}^{(u_1)} - 3k_{\{2,3\}}\psi_{\{2,3\}}^{(u_{\{2,3\}})} + \bar{M}_{2,3}^c$$

$$M_{4,3} = M_{4,3}^c = -3k_{\{3,4\}}\psi_{\{3,4\}}^{(u_1)} - 3k_{\{3,4\}}\psi_{\{3,4\}}^{(u_{\{2,3\}})} + \bar{M}_{4,3}^c$$



$$M_{1,2} = 2k_{\{1,2\}}\varphi_2 - 6k_{\{1,2\}}\frac{u_1}{3} - 6k_{\{1,2\}}\left(-\frac{u_{\{2,3\}}}{3}\right) + \bar{M}_{1,2}$$

$$= 2k_{\{1,2\}}\varphi_2 - 2k_{\{1,2\}}u_1 + 2k_{\{1,2\}}u_{\{2,3\}} + \bar{M}_{1,2}$$

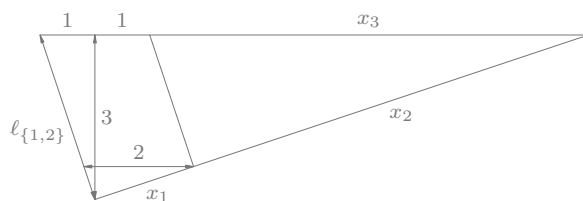
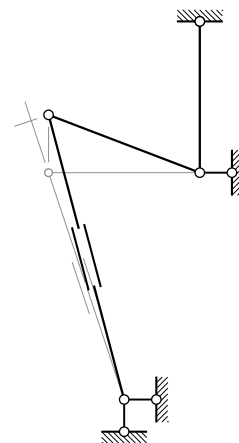
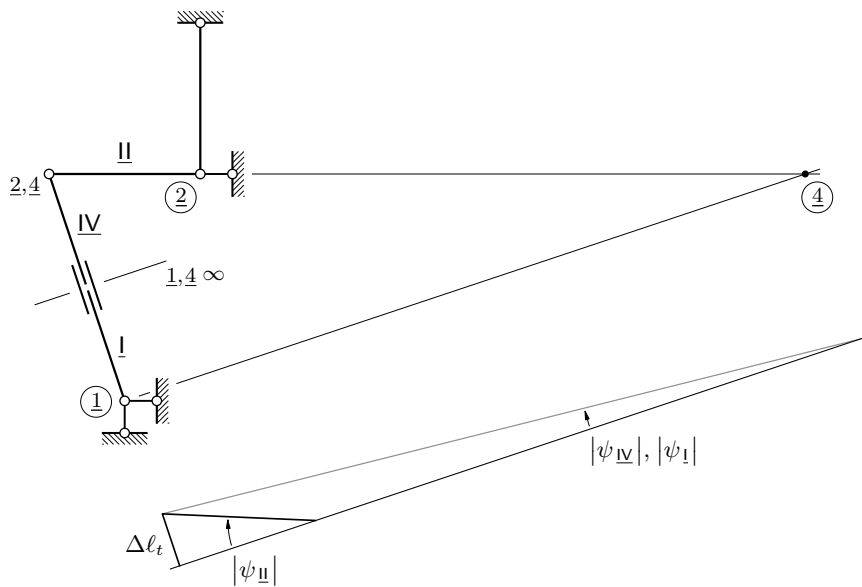
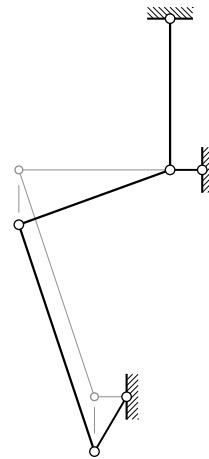
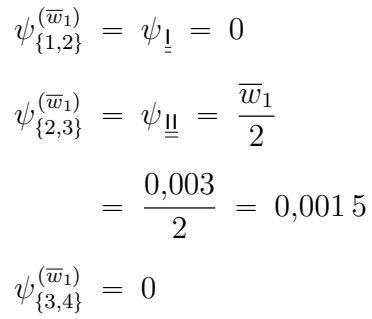
$$M_{2,1} = 4k_{\{1,2\}}\varphi_2 - 6k_{\{1,2\}}\frac{u_1}{3} - 6k_{\{1,2\}}\left(-\frac{u_{\{2,3\}}}{3}\right) + \bar{M}_{2,1}$$

$$= 4k_{\{1,2\}}\varphi_2 - 2k_{\{1,2\}}u_1 + 2k_{\{1,2\}}u_{\{2,3\}} + \bar{M}_{2,1}$$

$$M_{2,3} = M_{2,3}^c = 3k_{\{2,3\}}\varphi_2 - 3k_{\{2,3\}}\frac{u_1}{6} - 3k_{\{2,3\}}\left(-\frac{u_{\{2,3\}}}{6}\right) + \bar{M}_{2,3}^c$$

$$= 3k_{\{2,3\}}\varphi_2 - \frac{1}{2}k_{\{2,3\}}u_1 + \frac{1}{2}k_{\{2,3\}}u_{\{2,3\}} + \bar{M}_{2,3}^c$$

$$M_{4,3} = M_{4,3}^c = -3k_{\{3,4\}} \cdot 0 - 3k_{\{3,4\}}\frac{u_{\{2,3\}}}{2} + \bar{M}_{4,3}^c = -\frac{3}{2}k_{\{3,4\}}u_{\{2,3\}} + \bar{M}_{4,3}^c$$



$$t_s = \frac{t_1 + t_2}{2} = \frac{0 + 42}{2} = 21^\circ \text{C}$$

$$\Delta \ell_t = \alpha_t t_s \ell_{\{1,2\}} = 10^{-5} \cdot 21 \cdot \sqrt{10} = 0,000\,664 \text{ m}$$

$$\frac{x_1}{2} = \frac{3}{\ell_{\{1,2\}}} \quad \Rightarrow \quad x_1 = \frac{6}{\ell_{\{1,2\}}} = \frac{6}{\sqrt{10}} = 1,90 \text{ m}$$

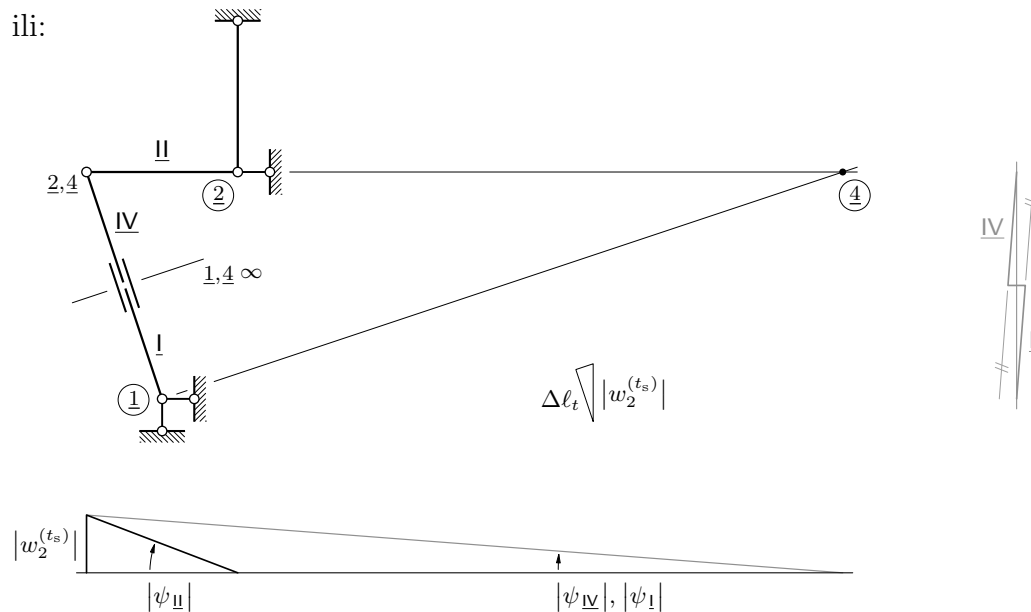
$$\frac{x_1 + x_2}{\ell_{\{1,2\}}} = \frac{3}{1} \Rightarrow x_1 + x_2 = 3 \ell_{\{1,2\}} = 9,48 \text{ m}$$

$$\psi_{\{2,3\}}^{(t_s)} = \psi_{\parallel} = -\frac{\Delta \ell_t}{x_1} = -\alpha_t t_s \ell_{\{1,2\}} \frac{\ell_{\{1,2\}}}{6} = -10^{-5} \cdot 21 \cdot \frac{(\sqrt{10})^2}{6} = -0,000\,350$$

$$\psi_{\{1,2\}}^{(t_s)} = \psi_{\perp} = -\frac{\Delta \ell_t}{x_1 + x_2} = -\frac{\alpha_t t_s \ell_{\{1,2\}}}{3 \ell_{\{1,2\}}} = -0,000\,070\,0$$

$$\psi_{\{3,4\}}^{(t_s)} = 0$$

ili:



objašnjenje trokut(ić)a sa stranicama $\Delta \ell_t$ i $|w_2^{(t_s)}|$:

$\vec{\Delta \ell_t}$ (vektor duljine $\Delta \ell_t$ na osi štapa $\{1, 2\}$) nije pomak $\vec{\delta}_2$ čvora 2, tako da ni projekcije vektora $\vec{\Delta \ell_t}$ na vertikalnu i na horizontalnu os nisu projekcije pomaka $\vec{\delta}_2$ na te osi; $\vec{\Delta \ell_t}$ je samo komponenta pomaka $\vec{\delta}_2$ na osi štapa $\{1, 2\}$, uzrokovana njegovim produljenjem. Osim što se produljuje, štap $\{1, 2\}$ se zbog spoja sa štapom $\{2, 3\}$ i zaokreće (oko pola 2), pa $\vec{\delta}_2$ ima i komponentu $\vec{w}_{1,2}$ okomitu na os štapa $\{1, 2\}$. Kako čvor 2 „pripada” i štapu $\{2, 3\}$, pomiče se po okomici na os toga štapa, tako da zbroj komponenata $\vec{\Delta \ell_t}$ i $\vec{w}_{1,2}$ pomaka $\vec{\delta}_2$ mora biti na toj okomici (pogledajte i plan pomaka na prethodnoj stranici), pa se $\vec{\delta}_2$ i njegova projekcija $\vec{w}_2$ na vertikalnu os (duljine $|w_2^{(t_s)}|$) poklapaju, $\vec{\delta}_2 = \vec{w}_2$, a projekcija $\vec{u}_2$ na horizontalnu os iščezava, $\vec{u}_2 = \vec{0}$, $u_2 = 0$.

$$\frac{|w_2^{(t_s)}|}{\Delta \ell_t} = \frac{\ell_{\{1,2\}}}{3} \Rightarrow |w_2^{(t_s)}| = \Delta \ell_t \frac{\ell_{\{1,2\}}}{3} = -10^{-5} \cdot 21 \cdot \frac{(\sqrt{10})^2}{3} = 0,000\,700 \text{ m}$$

$$\psi_{\{2,3\}}^{(t_s)} = \psi_{\parallel} = -\frac{|w_2^{(t_s)}|}{2} = -0,000\,350$$

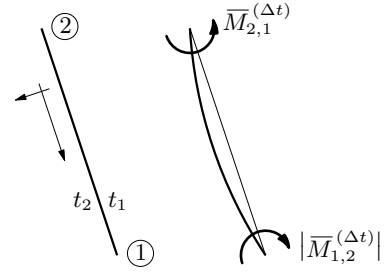
$$\frac{2 + x_3}{\ell_{\{1,2\}}} = \frac{\ell_{\{1,2\}}}{1} \Rightarrow 2 + x_3 = \ell_{\{1,2\}}^2 = 10 \text{ m} \quad (\text{prema skici na prethodnoj stranici})$$

$$\psi_{\{1,2\}}^{(t_s)} = \psi_{\perp} = -\frac{|w_2^{(t_s)}|}{2 + x_3} = -0,000\,070\,0$$

$$\Delta t = t_{\text{dolje}} - t_{\text{gore}} = t_2 - t_1 = 42 - 0 = 42^\circ \text{C}$$

$$\begin{aligned}\bar{M}_{2,1}^{(\Delta t)} &= (EI)_{\{1,2\}} \alpha_t \frac{\Delta t}{h_{\{1,2\}}} = 2EI \alpha_t \frac{\Delta t}{h_{\{1,2\}}} \\ &= 2 \cdot 162\,000 \cdot 10^{-5} \cdot \frac{42}{0,6} = 226,80 \text{ kNm}\end{aligned}$$

$$\bar{M}_{1,2}^{(\Delta t)} = -\bar{M}_{2,1}^{(\Delta t)} = -226,80 \text{ kNm}$$

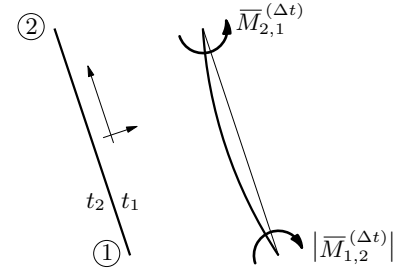


ili:

$$\Delta t = t_{\text{dolje}} - t_{\text{gore}} = t_1 - t_2 = 0 - 42 = -42^\circ \text{C}$$

$$\begin{aligned}\bar{M}_{1,2}^{(\Delta t)} &= 2EI \alpha_t \frac{\Delta t}{h_{\{1,2\}}} \\ &= 2 \cdot 162\,000 \cdot 10^{-5} \cdot \frac{-42}{0,6} = -226,80 \text{ kNm}\end{aligned}$$

$$\bar{M}_{2,1}^{(\Delta t)} = -\bar{M}_{1,2}^{(\Delta t)} = 226,80 \text{ kNm}$$



$${}^c\bar{M}_{4,3}^{(\bar{\varphi}_4)} = -3 k_{\{3,4\}} \bar{\varphi}_4$$

$$k_{\{1,2\}} = \frac{2EI}{\ell_{\{1,2\}}} = \frac{2 \cdot 162\,000}{\sqrt{10}} = 102\,458 \text{ kNm}$$

$$k_{\{2,3\}} = \frac{EI}{\ell_{\{2,3\}}} = \frac{162\,000}{2} = 81\,000 \text{ kNm}, \quad k_{\{3,4\}} = \frac{EI}{\ell_{\{3,4\}}} = 81\,000 \text{ kNm}$$

$$\begin{aligned}\bar{M}_{1,2} &= \bar{M}_{1,2}^{(\bar{w}_1)} + \bar{M}_{1,2}^{(t_s)} + \bar{M}_{1,2}^{(\Delta t)} = -6 k_{\{1,2\}} \psi_{\{1,2\}}^{(\bar{w}_1)} - 6 k_{\{1,2\}} \psi_{\{1,2\}}^{(t_s)} + \bar{M}_{1,2}^{(\Delta t)} \\ &= -6 \cdot 102\,458 \cdot 0 - 6 \cdot 102\,458 \cdot (-0,000\,07) - 226,80 = -183,77 \text{ kNm}\end{aligned}$$

$$\begin{aligned}\bar{M}_{2,1} &= \bar{M}_{2,1}^{(\bar{w}_1)} + \bar{M}_{2,1}^{(t_s)} + \bar{M}_{2,1}^{(\Delta t)} = -6 k_{\{1,2\}} \psi_{\{1,2\}}^{(\bar{w}_1)} - 6 k_{\{1,2\}} \psi_{\{1,2\}}^{(t_s)} + \bar{M}_{2,1}^{(\Delta t)} \\ &= -6 \cdot 102\,458 \cdot 0 - 6 \cdot 102\,458 \cdot (-0,000\,07) + 226,80 = 269,83 \text{ kNm}\end{aligned}$$

$$\begin{aligned}\bar{M}_{2,3}^c &= {}^c\bar{M}_{2,3}^{(\bar{w}_1)} + {}^c\bar{M}_{2,3}^{(t_s)} = -3 k_{\{2,3\}} \psi_{\{2,3\}}^{(\bar{w}_1)} - 3 k_{\{2,3\}} \psi_{\{2,3\}}^{(t_s)} \\ &= -3 \cdot 81\,000 \cdot 0,001\,5 - 3 \cdot 81\,000 \cdot (-0,000\,35) = -279,45 \text{ kNm}\end{aligned}$$

$$\bar{M}_{4,3}^c = {}^c\bar{M}_{4,3}^{(\bar{\varphi}_4)} = -3 k_{\{3,4\}} \bar{\varphi}_4 = -3 \cdot 81\,000 \cdot (-0,000\,6) = -145,80 \text{ kNm}$$

jednadžba ravnoteže momenata u čvoru 2:

$$-M_{2,1} - M_{2,3} = 0 \quad \Rightarrow \quad M_{2,1} + M_{2,3} = 0$$

$$\begin{aligned}
& [4 k_{\{1,2\}} \varphi_2 - 2 k_{\{1,2\}} u_1 + 2 k_{\{1,2\}} u_{\{2,3\}} + \bar{M}_{2,1}] \\
& + \left[3 k_{\{2,3\}} \varphi_2 - \frac{1}{2} k_{\{2,3\}} u_1 + \frac{1}{2} k_{\{2,3\}} u_{\{2,3\}} + \bar{M}_{2,3}^c \right] = 0 \\
& (4 k_{\{1,2\}} + 3 k_{\{2,3\}}) \varphi_2 + \left(-2 k_{\{1,2\}} - \frac{1}{2} k_{\{2,3\}} \right) u_1 \\
& + \left(2 k_{\{1,2\}} + \frac{1}{2} k_{\{2,3\}} \right) u_{\{2,3\}} = -\bar{M}_{2,1} - \bar{M}_{2,3}^c \\
& 652\,832 \cdot \varphi_2 - 245\,416 \cdot u_1 + 245\,416 \cdot u_{2,3} = -269,83 - (-279,45) \\
& 652\,832 \cdot \varphi_2 - 245\,416 \cdot u_1 + 245\,416 \cdot u_{2,3} = 9,62 \quad (\clubsuit\clubsuit\clubsuit)
\end{aligned}$$

jednadžba rada na virtualnom pomaku δu_1 (projekcije pomaka za u_1 uz dodani δ):

$$\begin{aligned}
& (M_{1,2} + M_{2,1}) \delta \psi_{\{1,2\}}^{(\delta u_1)} + M_{2,3} \delta \psi_{\{2,3\}}^{(\delta u_1)} + M_{4,3} \delta \psi_{\{3,4\}}^{(\delta u_1)} = 0 \\
& (6 k_{\{1,2\}} \varphi_2 - 4 k_{\{1,2\}} u_1 + 4 k_{\{1,2\}} u_{2,3} + \bar{M}_{1,2} + \bar{M}_{2,1}) \frac{\delta u_1}{3} \\
& + \left(3 k_{\{2,3\}} \varphi_2 - \frac{1}{2} k_{\{2,3\}} u_1 + \frac{1}{2} k_{\{2,3\}} u_{2,3} + \bar{M}_{2,3}^c \right) \frac{\delta u_1}{6} \\
& + \left(-\frac{3}{2} k_{\{3,4\}} u_{2,3} + \bar{M}_{4,3}^c \right) \cdot 0 = 0 \quad \forall \delta u_1 \\
& \left(2 k_{\{1,2\}} + \frac{1}{2} k_{\{2,3\}} \right) \varphi_2 - \left(\frac{4}{3} k_{\{1,2\}} + \frac{1}{12} k_{\{2,3\}} \right) u_1 \\
& + \left(\frac{4}{3} k_{\{1,2\}} + \frac{1}{12} k_{\{2,3\}} \right) u_{2,3} = -\frac{1}{3} (\bar{M}_{1,2} + \bar{M}_{2,1}) - \frac{1}{6} \bar{M}_{2,3}^c \\
& 245\,416 \varphi_2 - 143\,361 u_1 + 143\,361 u_{2,3} = -\frac{1}{3} \cdot (-183,77 + 269,83) - \frac{1}{6} \cdot (-279,45) \\
& 245\,416 \varphi_2 - 143\,361 u_1 + 143\,361 u_{2,3} = 17,89 \quad \Big| \quad \times (-1) \\
& -245\,416 \varphi_2 + 143\,361 u_1 - 143\,361 u_{2,3} = -17,89 \quad (\clubsuit\cancel{\clubsuit})
\end{aligned}$$

jednadžba rada na virtualnom pomaku $\delta u_{2,3}$ (projekcije pomaka za $u_{2,3}$ uz dodani δ):

$$\begin{aligned}
& (M_{1,2} + M_{2,1}) \delta \psi_{\{1,2\}}^{(\delta u_{\{2,3\}})} + M_{2,3} \delta \psi_{\{2,3\}}^{(\delta u_{\{2,3\}})} + M_{4,3} \delta \psi_{\{3,4\}}^{(\delta u_{\{2,3\}})} = 0 \\
& (6 k_{\{1,2\}} \varphi_2 - 4 k_{\{1,2\}} u_1 + 4 k_{\{1,2\}} u_{2,3} + \bar{M}_{1,2} + \bar{M}_{2,1}) \left(-\frac{\delta u_{2,3}}{3} \right) \\
& + \left(3 k_{\{2,3\}} \varphi_2 - \frac{1}{2} k_{\{2,3\}} u_1 + \frac{1}{2} k_{\{2,3\}} u_{2,3} + \bar{M}_{2,3}^c \right) \left(-\frac{\delta u_{2,3}}{6} \right) \\
& + \left(-\frac{3}{2} k_{\{3,4\}} u_{2,3} + \bar{M}_{4,3}^c \right) \frac{\delta u_{2,3}}{2} = 0 \quad \forall \delta u_1
\end{aligned}$$

$$\begin{aligned}
& - \left(2 k_{\{1,2\}} + \frac{1}{2} k_{\{2,3\}} \right) \varphi_2 + \left(\frac{4}{3} k_{\{1,2\}} + \frac{1}{12} k_{\{2,3\}} \right) u_1 \\
& - \left(\frac{4}{3} k_{\{1,2\}} + \frac{1}{12} k_{\{2,3\}} + \frac{3}{4} k_{\{3,4\}} \right) u_{2,3} \\
& = \frac{1}{3} (\overline{M}_{1,2} + \overline{M}_{2,1}) + \frac{1}{6} \overline{M}_{2,3}^c - \frac{1}{2} \overline{M}_{4,3}^c \\
& -245\,416 \varphi_2 + 143\,361 u_1 - 204\,111 u_{2,3} \\
& = \frac{1}{3} \cdot (-183,77 + 269,83) + \frac{1}{6} \cdot (-279,45) - \frac{1}{2} \cdot (-145,80) \\
& -245\,416 \varphi_2 + 143\,361 u_1 - 204\,111 u_{2,3} = 55,01 \quad \Bigg| \quad \times (-1) \\
& 245\,416 \varphi_2 - 143\,361 u_1 + 204\,111 u_{2,3} = -55,01 \quad (\text{---})
\end{aligned}$$

rješenje sustava jednažbi (---) , (---) i (---) :

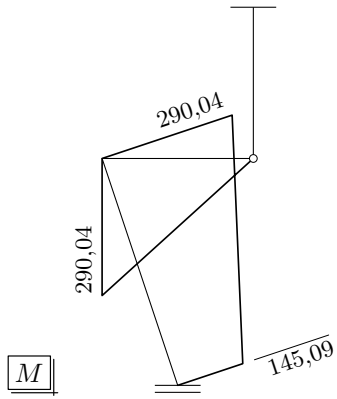
$$\varphi_2 = -0,000\,090\,26, \quad u_1 = -0,001\,479 \text{ m} \quad \& \quad u_{\{2,3\}} = -0,001\,2 \text{ m}$$

vrijednosti momenata na krajevima štapova:

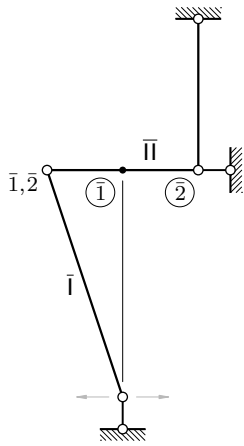
$$\begin{aligned}
M_{1,2} &= k_{\{1,2\}} (2 \varphi_2 - 2 u_1 + 2 u_{\{2,3\}}) + \overline{M}_{1,2} \\
&= 102\,458 \cdot [2 \cdot (-0,000\,090\,26) - 2 \cdot (-0,001\,479) + 2 \cdot (-0,001\,2)] - 183,77 \\
&= -145,09 \text{ kNm} \\
M_{2,1} &= k_{\{1,2\}} (4 \varphi_2 - 2 u_1 + 2 u_{\{2,3\}}) + \overline{M}_{2,1} \\
&= 102\,458 \cdot [4 \cdot (-0,000\,090\,26) - 2 \cdot (-0,001\,479) + 2 \cdot (-0,001\,2)] + 269,83 \\
&= 290,01 \text{ kNm} \\
M_{2,3} &= k_{\{2,3\}} \left(3 \varphi_2 - \frac{1}{2} u_1 + \frac{1}{2} u_{\{2,3\}} \right) + \overline{M}_{2,3}^c \\
&= 81\,000 \cdot \left[3 \cdot (-0,000\,090\,26) - \frac{1}{2} \cdot (-0,001\,479) + \frac{1}{2} \cdot (-0,001\,2) \right] - 279,45 \\
&= -290,08 \text{ kNm} \\
M_{4,3} &= -\frac{3}{2} k_{\{3,4\}} u_{\{2,3\}} + \overline{M}_{4,3}^c = -\frac{3}{2} \cdot 81\,000 \cdot (-0,001\,2) - 145,80 = 0
\end{aligned}$$

(„neravnoteža” momenata u čvoru 2 posljedica je pogrešaka zaokruživanja)

momentni dijagram:



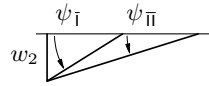
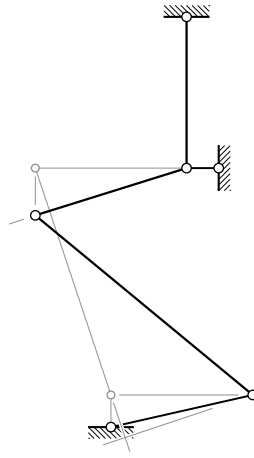
b.



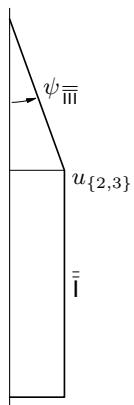
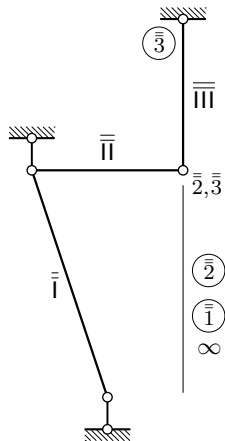
$$\psi_{\{1,2\}}^{(w_2)} = \psi_{\bar{1}} = \frac{w_2}{1}$$

$$\psi_{\{2,3\}}^{(w_2)} = \psi_{\overline{\Pi}} = \frac{w_2}{2}$$

$$\psi_{\{3,4\}}^{(w_2)} = 0$$



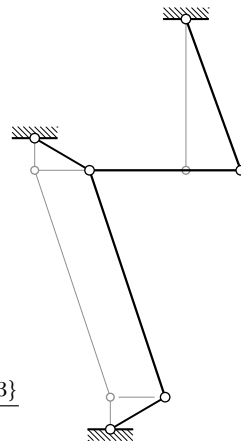
(isti mehanizam kao za $\vec{u}_1$ u a., ali je „vodeći” pomak sada $\vec{w}_2$)



$$\psi_{\{1,2\}}^{(u_{\{2,3\}})} = 0$$

$$\psi_{\{2,3\}}^{(u_{\{2,3\}})} = 0$$

$$\psi_{\{3,4\}}^{(u_{\{2,3\}})} = \psi_{\overline{\text{III}}} = \frac{u_{\{2,3\}}}{2}$$

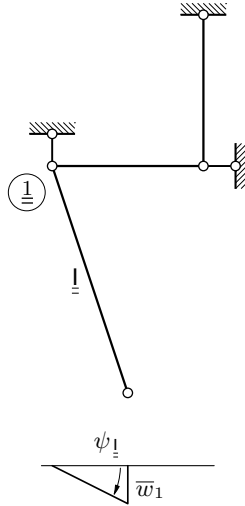


$$\begin{aligned}
M_{1,2} &= 2 k_{\{1,2\}} \varphi_2 - 6 k_{\{1,2\}} \psi_{\{1,2\}}^{(w_2)} - 6 k_{\{1,2\}} \psi_{\{1,2\}}^{(u_{\{2,3\}})} + \bar{M}_{1,2} \\
&= 2 k_{\{1,2\}} \varphi_2 - 6 k_{\{1,2\}} w_2 + \bar{M}_{1,2}
\end{aligned}$$

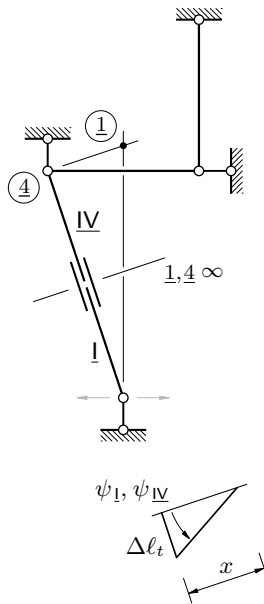
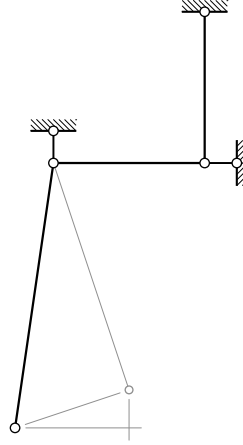
$$\begin{aligned}
M_{2,1} &= 4 k_{\{1,2\}} \varphi_2 - 6 k_{\{1,2\}} \psi_{\{1,2\}}^{(w_2)} - 6 k_{\{1,2\}} \psi_{\{1,2\}}^{(u_{\{2,3\}})} + \bar{M}_{2,1} \\
&= 4 k_{\{1,2\}} \varphi_2 - 6 k_{\{1,2\}} w_2 + \bar{M}_{2,1}
\end{aligned}$$

$$\begin{aligned}
M_{2,3} &= M_{2,3}^c = 3 k_{\{2,3\}} \varphi_2 - 3 k_{\{2,3\}} \psi_{\{2,3\}}^{(w_2)} - 3 k_{\{2,3\}} \psi_{\{2,3\}}^{(u_{\{2,3\}})} + \bar{M}_{2,3}^c \\
&= 3 k_{\{2,3\}} \varphi_2 - \frac{3}{2} k_{\{2,3\}} w_2 + \bar{M}_{2,3}^c
\end{aligned}$$

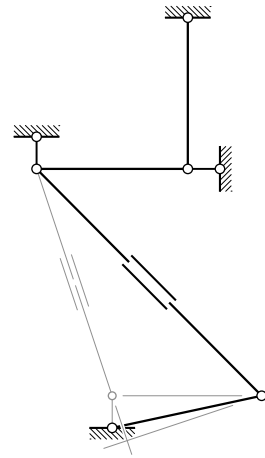
$$\begin{aligned}
M_{4,3} &= M_{4,3}^c = -3 k_{\{3,4\}} \psi_{\{3,4\}}^{(w_2)} - 3 k_{\{3,4\}} \psi_{\{3,4\}}^{(u_{\{2,3\}})} + \bar{M}_{4,3}^c \\
&= -\frac{3}{2} k_{\{3,4\}} u_{\{2,3\}} + \bar{M}_{4,3}^c
\end{aligned}$$



$$\begin{aligned}
\psi_{\{1,2\}}^{(\bar{w}_1)} &= \psi_I = -\frac{\bar{w}_1}{1} \\
&= -0,003 \\
\psi_{\{2,3\}}^{(\bar{w}_1)} &= \psi_{\{3,4\}}^{(\bar{w}_1)} = 0
\end{aligned}$$



$$\begin{aligned}
\frac{x}{1} &= \frac{\ell_{\{1,2\}}}{3} \Rightarrow x = \frac{\ell_{\{1,2\}}}{3} \\
\psi_{\{1,2\}}^{(t_s)} &= \psi_I = \frac{\Delta \ell_t}{x} \\
&= \frac{3 \Delta \ell_t}{\ell_{\{1,2\}}} = 0,000\,630 \\
\psi_{\{2,3\}}^{(t_s)} &= \psi_{\{3,4\}}^{(t_s)} = 0
\end{aligned}$$



$$\begin{aligned}
\bar{M}_{1,2} &= \bar{M}_{1,2}^{(\bar{w}_1)} + \bar{M}_{1,2}^{(t_s)} + \bar{M}_{1,2}^{(\Delta t)} = -6 k_{\{1,2\}} \psi_{\{1,2\}}^{(\bar{w}_1)} - 6 k_{\{1,2\}} \psi_{\{1,2\}}^{(t_s)} + \bar{M}_{1,2}^{(\Delta t)} \\
&= -6 \cdot 102\,458 \cdot (-0,003) - 6 \cdot 102\,458 \cdot 0,000\,63 - 226,80 = 1\,230,15 \text{ kNm} \\
\bar{M}_{2,1} &= \bar{M}_{2,1}^{(\bar{w}_1)} + \bar{M}_{2,1}^{(t_s)} + \bar{M}_{2,1}^{(\Delta t)} = -6 k_{\{1,2\}} \psi_{\{1,2\}}^{(\bar{w}_1)} - 6 k_{\{1,2\}} \psi_{\{1,2\}}^{(t_s)} + \bar{M}_{2,1}^{(\Delta t)} \\
&= -6 \cdot 102\,458 \cdot (-0,003) - 6 \cdot 102\,458 \cdot 0,000\,63 + 226,80 = 1\,683,75 \text{ kNm} \\
\bar{M}_{2,3}^c &= {}^c\bar{M}_{2,3}^{(\bar{w}_1)} + {}^c\bar{M}_{2,3}^{(t_s)} = -3 k_{\{2,3\}} \psi_{\{2,3\}}^{(\bar{w}_1)} - 3 k_{\{2,3\}} \psi_{\{2,3\}}^{(t_s)} = 0 \\
\bar{M}_{4,3}^c &= {}^c\bar{M}_{4,3}^{(\bar{\varphi}_4)} = -3 k_{\{3,4\}} \bar{\varphi}_4 = -3 \cdot 81\,000 \cdot (-0,000\,6) = -145,80 \text{ kNm}
\end{aligned}$$

jednadžba ravnoteže momenata u čvoru 2:

$$\begin{aligned}
-M_{2,1} - M_{2,3} &= 0 \quad \Rightarrow \quad M_{2,1} + M_{2,3} = 0 \\
[4 k_{\{1,2\}} \varphi_2 - 6 k_{\{1,2\}} w_2 + \bar{M}_{2,1}] + \left[3 k_{\{2,3\}} \varphi_2 - \frac{3}{2} k_{\{2,3\}} w_2 + \bar{M}_{2,3}^c \right] &= 0 \\
(4 k_{\{1,2\}} + 3 k_{\{2,3\}}) \varphi_2 + \left(-6 k_{\{1,2\}} - \frac{3}{2} k_{\{2,3\}} \right) w_2 &= -\bar{M}_{2,1} - \bar{M}_{2,3}^c \\
652\,832 \cdot \varphi_2 - 736\,248 \cdot w_2 &= -1\,683,75 \quad (\text{b})
\end{aligned}$$

jednadžba rada na virtualnom pomaku δw_2 :

$$\begin{aligned}
(M_{1,2} + M_{2,1}) \delta \psi_{\{1,2\}}^{(\delta w_2)} + M_{2,3} \delta \psi_{\{2,3\}}^{(\delta w_2)} + M_{4,3} \delta \psi_{\{3,4\}}^{(\delta w_2)} &= 0 \\
(6 k_{\{1,2\}} \varphi_2 - 12 k_{\{1,2\}} w_2 + \bar{M}_{1,2} + \bar{M}_{2,1}) \delta w_2 &+ \left(3 k_{\{2,3\}} \varphi_2 - \frac{3}{2} k_{\{2,3\}} w_2 + \bar{M}_{2,3}^c \right) \frac{\delta w_2}{2} + \left(-\frac{3}{2} k_{\{3,4\}} u_{\{2,3\}} + \bar{M}_{4,3}^c \right) \cdot 0 = 0 \\
\left(6 k_{\{1,2\}} + \frac{3}{2} k_{\{2,3\}} \right) \varphi_2 - \left(12 k_{\{1,2\}} + \frac{3}{4} k_{\{2,3\}} \right) w_2 &= -\bar{M}_{1,2} - \bar{M}_{2,1} - \frac{1}{2} \bar{M}_{2,3}^c \\
736\,248 \varphi_2 - 1\,290\,246 w_2 &= -1\,230,15 - 1\,683,75 - \frac{1}{2} \cdot 0 \\
736\,248 \varphi_2 - 1\,290\,246 w_2 &= -2\,913,90 \quad \Bigg| \quad \times (-1) \\
-736\,248 \varphi_2 + 1\,290\,246 w_2 &= 2\,913,90 \quad (\text{b})
\end{aligned}$$

jednadžba rada na virtualnom pomaku $\delta u_{2,3}$:

$$\begin{aligned}
(M_{1,2} + M_{2,1}) \delta \psi_{\{1,2\}}^{(\delta u_{\{2,3\}})} + M_{2,3} \delta \psi_{\{2,3\}}^{(\delta u_{\{2,3\}})} + M_{4,3} \delta \psi_{\{3,4\}}^{(\delta u_{\{2,3\}})} &= 0 \\
(M_{1,2} + M_{2,1}) \cdot 0 + M_{2,3} \cdot 0 + M_{4,3} \delta \psi_{\{3,4\}}^{(\delta u_{\{2,3\}})} &= 0 \\
\left(-\frac{3}{2} k_{\{3,4\}} u_{\{2,3\}} + \bar{M}_{4,3}^c \right) \frac{\delta u_{2,3}}{2} &= 0 \\
-60\,750 u_{\{2,3\}} &= 72,9 \quad \Bigg| \quad \times (-1) \\
60\,750 u_{\{2,3\}} &= -72,9 \quad (\text{b})
\end{aligned}$$

rješenje sustava jednažbi (---b), (---b) i (---b):

iz (---b) neposredno: $u_{\{2,3\}} = -0,0012 \text{ m}$

iz (---b) i (---b): $\varphi_2 = -0,00009025$ i $w_2 = 0,002207 \text{ m}$

vrijednosti momenata na krajevima štapova:

$$\begin{aligned} M_{1,2} &= k_{\{1,2\}} (2\varphi_2 - 6w_2) + \bar{M}_{1,2} \\ &= 102458 \cdot [2 \cdot (-0,00009025) - 6 \cdot 0,002207] + 1230,15 = -145,09 \text{ kNm} \end{aligned}$$

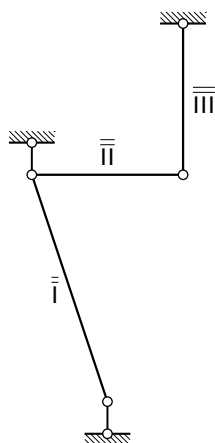
$$\begin{aligned} M_{2,1} &= k_{\{1,2\}} (4\varphi_2 - 6w_2) + \bar{M}_{1,2} \\ &= 102458 \cdot [4 \cdot (-0,00009025) - 6 \cdot 0,002207] + 1683,75 = 290,01 \text{ kNm} \end{aligned}$$

$$\begin{aligned} M_{2,3} &= k_{\{2,3\}} \left(3\varphi_2 - \frac{3}{2}w_2 \right) + \bar{M}_{2,3}^c \\ &= 81000 \cdot \left[3 \cdot (-0,00009025) - \frac{3}{2} \cdot 0,002207 \right] + 0 = -290,08 \text{ kNm} \end{aligned}$$

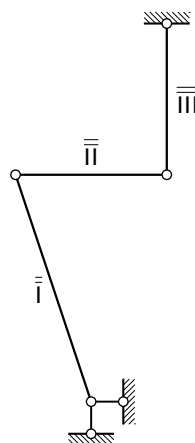
$$M_{4,3} = -\frac{3}{2} k_{\{3,4\}} u_{\{2,3\}} + \bar{M}_{4,3}^c = -\frac{3}{2} \cdot 81000 \cdot (-0,0012) - 145,80 = 0$$

momentni dijagram na vrhu stranice 8

c.

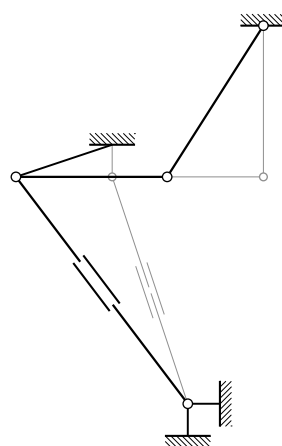
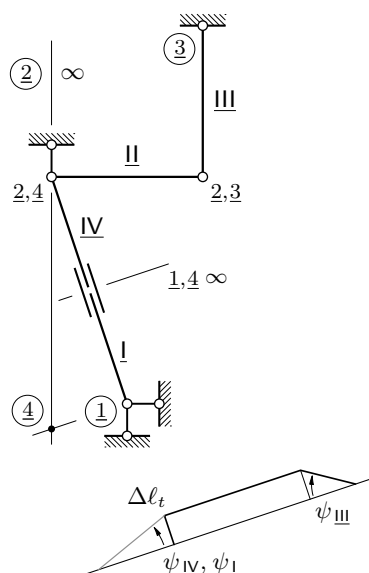
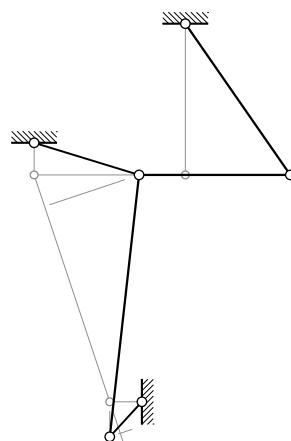
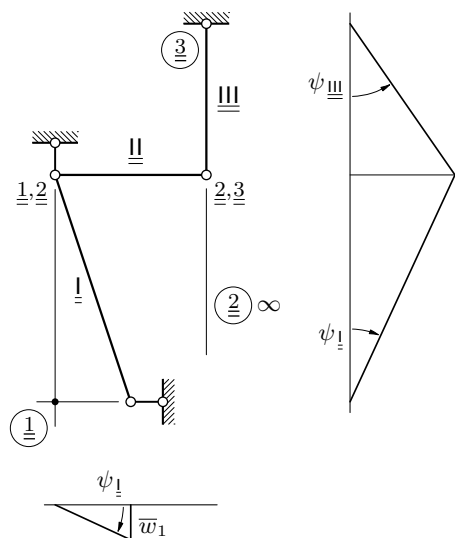


isti mehanizam kao za $\vec{u}_{\{2,3\}}$ u b.,
ali s drugim „vodećim” pomakom
— nastavite sami!



isti mehanizam kao za $\vec{u}_{\{2,3\}}$ u a.,
ali s drugim „vodećim” pomakom
— nastavite sami!

Prije no što okrenete stranicu, pokušajte sami nacrtati dijagrame projekcija pomaka i(li) planove pomaka za zadani prisilni pomak i za utjecaj promjene temperature!



Proračun provedite sami!